



## *Week 4 Lecture Notes*

# **Distributed Memory Programming Using Advanced MPI (Message Passing Interface)**



## MPI\_Bcast

**MPI\_Bcast(void \*message, int count, MPI\_Datatype dtype, int source, MPI\_Comm comm)**

- Collective communication
- Allows a process to broadcast a message to all other processes

```
MPI_Comm_size(MPI_COMM_WORLD,&numprocs);
MPI_Comm_rank(MPI_COMM_WORLD,&myid);
while(1)
{
    if (myid == 0)
    {
        printf("Enter the number of intervals: (0 quits) \n");
        fflush(stdout);
        scanf("%d",&n);
    } // if myid == 0
    MPI_Bcast(&n,1,MPI_INT,0,MPI_COMM_WORLD);
```



## MPI\_Reduce

```
MPI_Reduce(void *send_buf, void *recv_buf, int count, MPI_Datatype dtype, MPI_Op op
int root, MPI_Comm comm)
```

- Collective communication
- Processes perform the specified “reduction”
- The “root” has the results

```
if (myid == 0)
{
    printf("Enter the number of intervals: (0 quits) \n");
    fflush(stdout);
    scanf("%d",&n);
} // if myid == 0
MPI_Bcast(&n,1,MPI_INT,0,MPI_COMM_WORLD);
if (n == 0) break;
else
{
    h = 1.0 / (double) n;
    sum = 0.0;
    for (i = myid + 1; i <= n; i+= numprocs)
    {
        x = h * ((double)i - 0.5);
        sum += (4.0 / (1.0 + x*x));
    } // for
    mypi = h * sum;
MPI_Reduce(&mypi,&pi,1,MPI_DOUBLE,MPI_SUM,0,MPI_COMM_WORLD);
    if (myid == 0)
        printf("pi is approximately %.16f, Error is %.16f\n",
               pi, fabs(pi - PI25DT));
```



## MPI\_Allreduce

```
MPI_Allreduce(void *send_buf, void *recv_buf, int count, MPI_Datatype dtype, MPI_Op op,
                  MPI_Comm comm)
```

- Collective communication
- Processes perform the specified “reduction”
- All processes have the results

```
start = MPI_Wtime();
for (i=0; i<100; i++)
{
    a[i] = i;
    b[i] = i * 10;
    c[i] = i + 7;
    a[i] = b[i] * c[i];
}
end = MPI_Wtime();
printf("Our timers precision is %.20f seconds\n",MPI_Wtick());
printf("This silly loop took %.5f seconds\n",end-start);
}
else
{
    sprintf(sig,"Hello from id %d, %d or %d processes\n",myid,myid
+1,numprocs);
    MPI_Send(sig,sizeof(sig),MPI_CHAR,0,0,MPI_COMM_WORLD);
}
MPI_Allreduce(&myid,&sum,1,MPI_INT,MPI_SUM,MPI_COMM_WORLD);
printf("Sum of all process ids = %d\n",sum);
MPI_Finalize();
return 0;
}
```



## MPI Reduction Operators

- |                     |                                 |
|---------------------|---------------------------------|
| • <b>MPI_BAND</b>   | bitwise and                     |
| • <b>MPI_BOR</b>    | bitwise or                      |
| • <b>MPI_BXOR</b>   | bitwise exclusive or            |
| • <b>MPI_LAND</b>   | logical and                     |
| • <b>MPI_LOR</b>    | logical or                      |
| • <b>MPI_LXOR</b>   | logical exclusive or            |
| • <b>MPI_MAX</b>    | maximum                         |
| • <b>MPI_MAXLOC</b> | maximum and location of maximum |
| • <b>MPI_MIN</b>    | minimum                         |
| • <b>MPI_MINLOC</b> | minimum and location of minimum |
| • <b>MPI_PROD</b>   | product                         |
| • <b>MPI_SUM</b>    | sum                             |



## MPI\_Gather (example 1)

`MPI_Gather ( sendbuf, sendcnt, sendtype, recvbuf, recvcount, recvtype, root, comm )`

- Collective communication
- Root gathers data from every process including itself

```
#include <stdio.h>
#include <mpi.h>
#include <malloc.h>

int main(int argc, char **argv )
{
    int i,myid, numprocs;
    int *ids;
    MPI_Status status;

    MPI_Init(&argc, &argv);
    MPI_Comm_size(MPI_COMM_WORLD, &numprocs);
    MPI_Comm_rank(MPI_COMM_WORLD, &myid);
    if (myid == 0)
        ids = (int *) malloc(numprocs * sizeof(int));
    MPI_Gather(&myid,1,MPI_INT,ids,1,MPI_INT,0,MPI_COMM_WORLD);
    if (myid == 0)
        for (i=0;i<numprocs;i++)
            printf("%d\n",ids[i]);
    MPI_Finalize();
    return 0;
}
```



## MPI\_Gather (example 2)

**MPI\_Gather ( sendbuf, sendcnt, sendtype, recvbuf, recvcount, recvtype, root, comm )**

```
include <stdio.h>
#include <mpi.h>
#include <malloc.h>

int main(int argc, char **argv )
{
    int i,myid, numprocs;
    char sig[80];
    char *signatures;
    char **sigs;
    MPI_Status status;
    MPI_Init(&argc, &argv);
    MPI_Comm_size(MPI_COMM_WORLD, &numprocs);
    MPI_Comm_rank(MPI_COMM_WORLD, &myid);
    sprintf(sig,"Hello from id %d\n",myid);
    if (myid == 0)
        signatures = (char *) malloc(numprocs * sizeof(sig));
    MPI_Gather(&sig,sizeof(sig),MPI_CHAR,signatures,sizeof(sig),MPI_CHAR,
              0,MPI_COMM_WORLD);
    if (myid == 0)
    {
        sigs=(char **) malloc(numprocs * sizeof(char *));
        for(i=0;i<numprocs;i++)
        {
            sigs[i]=&signatures[i*sizeof(sig)];
            printf("%s",sig[i]);
        }
    }
    MPI_Finalize();
    return 0;
}
```



## MPI\_Alltoall

**MPI\_Alltoall( sendbuf, sendcount, sendtype, recvbuf, recvcnt, recvtype, comm )**

- **Collective communication**
- **Each process sends & receives the same amount of data to every process including itself**

```
#include <stdio.h>
#include <mpi.h>
#include <malloc.h>

int main(int argc, char **argv )
{
    int i,myid, numprocs;
    int *all,*ids;
    MPI_Status status;

    MPI_Init(&argc, &argv);
    MPI_Comm_size(MPI_COMM_WORLD, &numprocs);
    MPI_Comm_rank(MPI_COMM_WORLD, &myid);
    ids = (int *) malloc(numprocs * 3 * sizeof(int));
    all = (int *) malloc(numprocs * 3 * sizeof(int));
    for (i=0;i<numprocs*3;i++) ids[i] = myid;
    MPI_Alltoall(ids,3,MPI_INT,all,3,MPI_INT,MPI_COMM_WORLD);
    for (i=0;i<numprocs*3;i++)
        printf("%d\n",all[i]);
    MPI_Finalize();
    return 0;
}
```

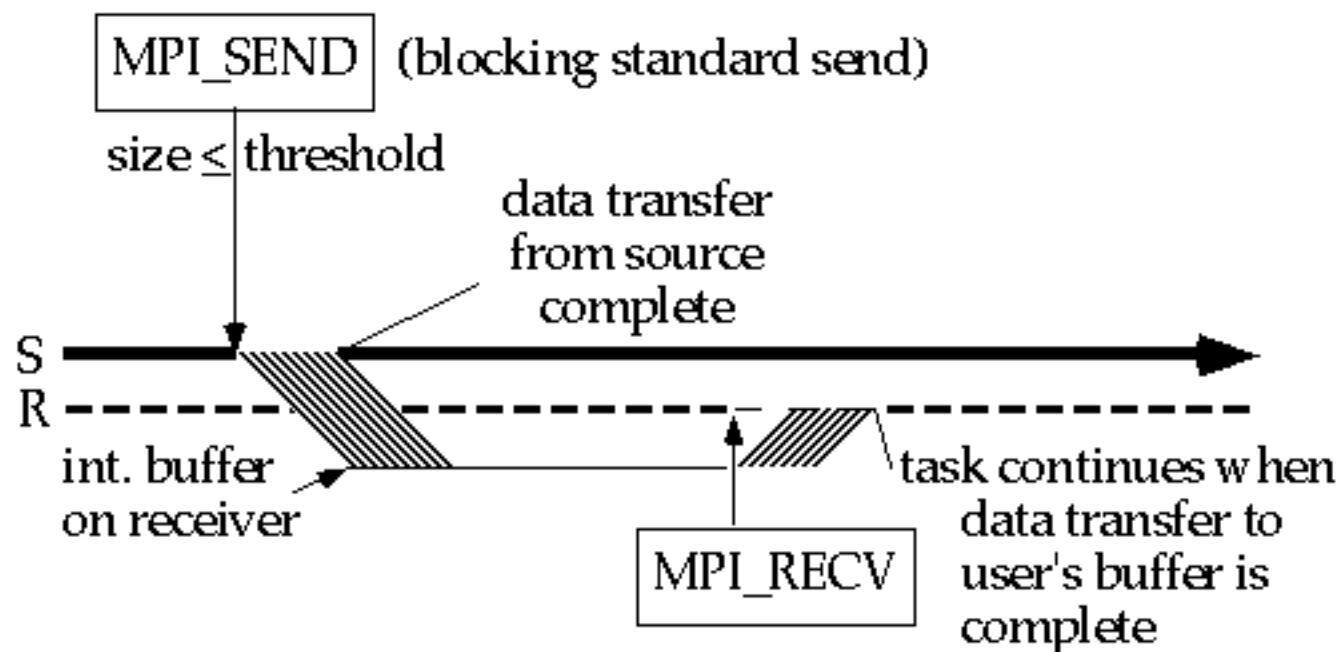
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## Different Modes for MPI\_Send – 1 of 4

### MPI\_Send: Standard send

- **`MPI_Send( buf, count, datatype, dest, tag, comm )`**
  - Quick return based on successful “buffering” on receive side
  - Behavior is implementation dependent and can be modified at runtime

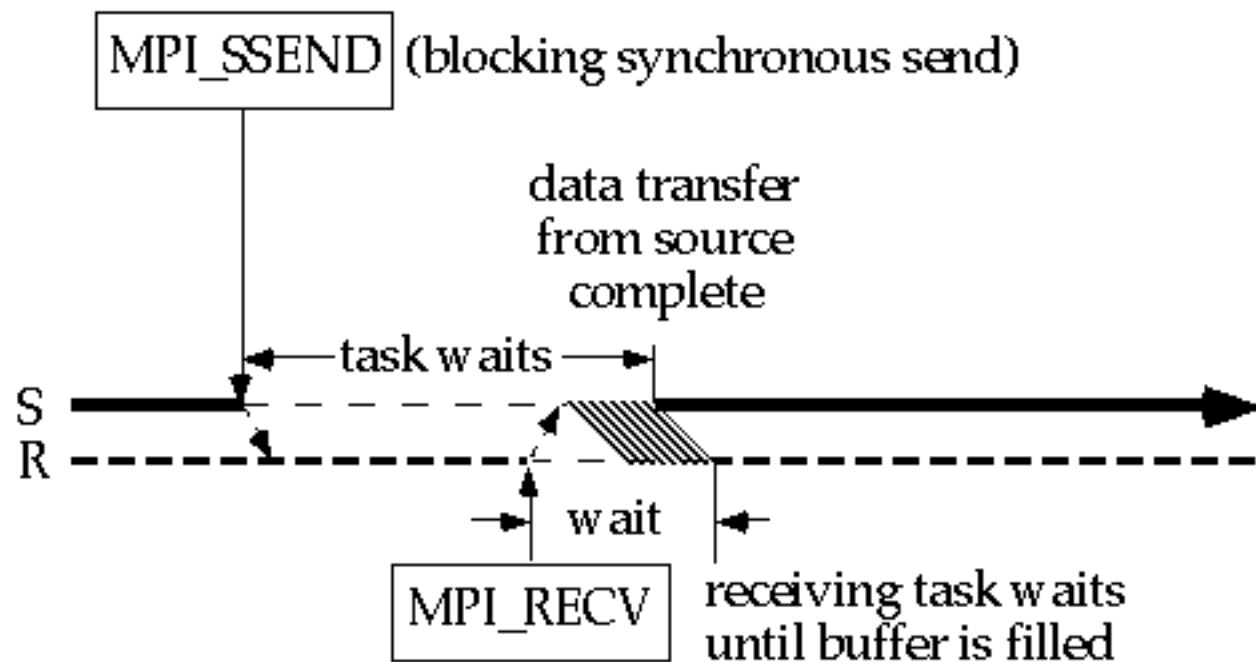




## Different Modes for MPI\_Send – 2 of 4

### MPI\_Ssend: Synchronous send

- **MPI\_Ssend( buf, count, datatype, dest, tag, comm )**
  - Returns after matching receive has begun and all data have been sent
  - This is also the behavior of MPI\_Send for message size > threshold

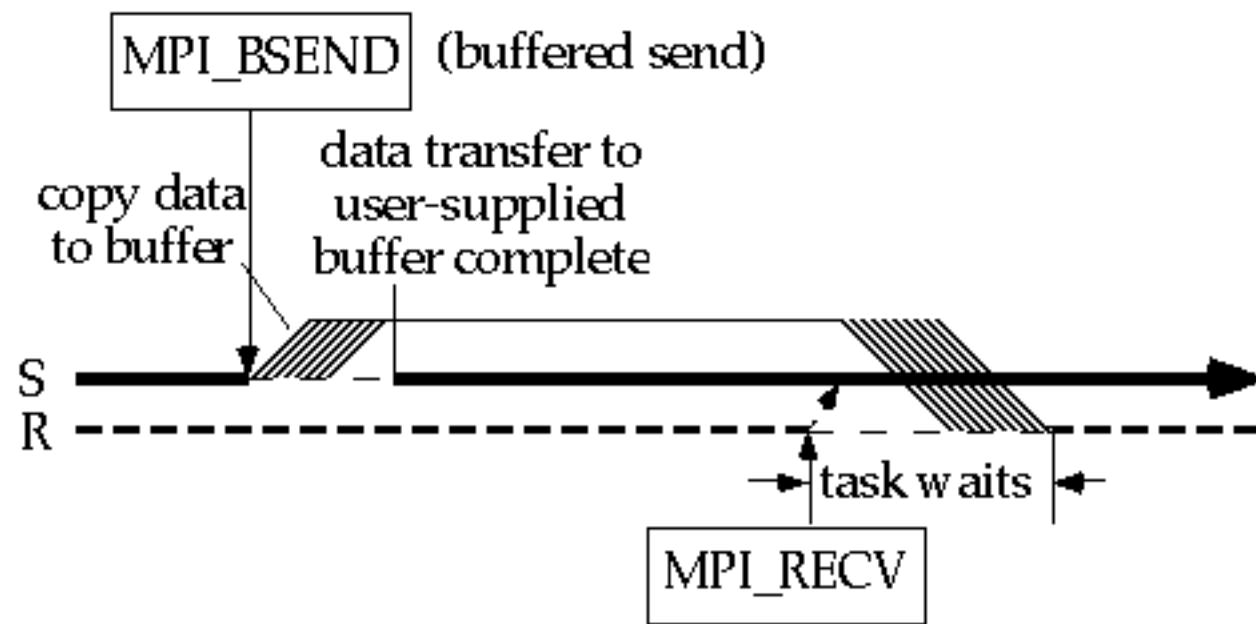




## Different Modes for MPI\_Send – 3 of 4

### MPI\_Bsend: Buffered send

- **MPI\_Bsend( buf, count, datatype, dest, tag, comm )**
  - Basic send with user specified buffering via MPI\_Buffer\_Attach
  - MPI must buffer outgoing send and return
  - Allows memory holding the original data to be changed

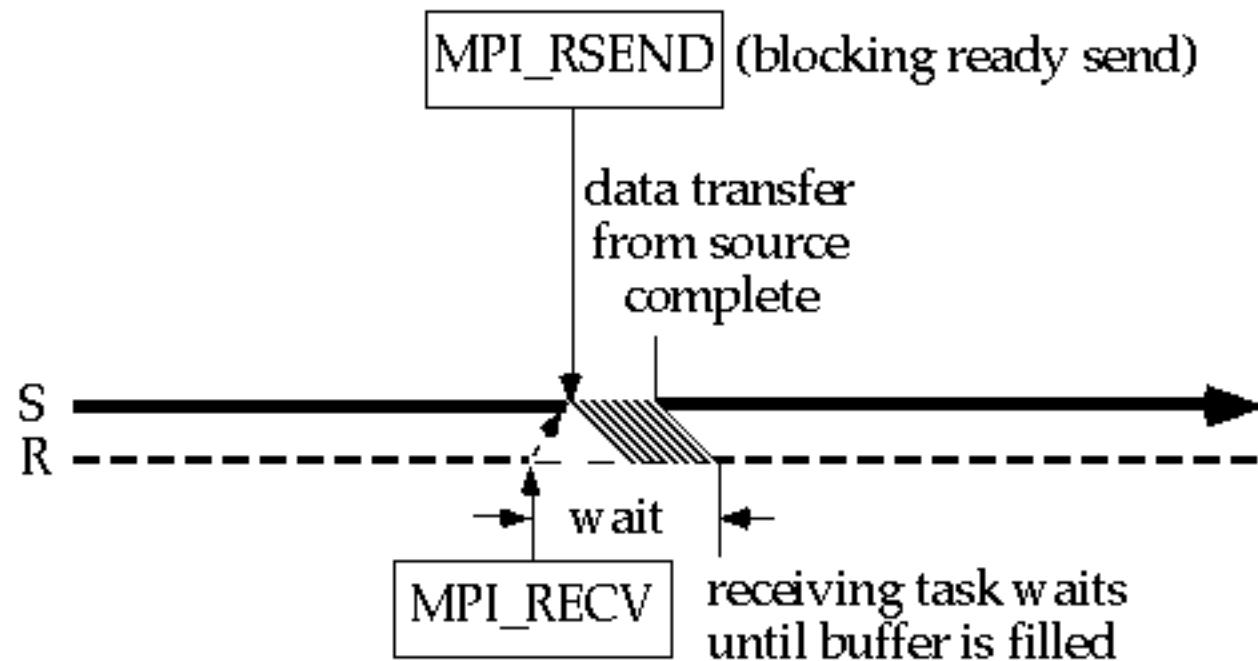




## Different Modes for MPI\_Send – 4 of 4

### MPI\_Rsend: Ready send

- **MPI\_Rsend( buf, count, datatype, dest, tag, comm )**
  - Send only succeeds if the matching receive is already posted
  - If the matching receive has not been posted, an error is generated





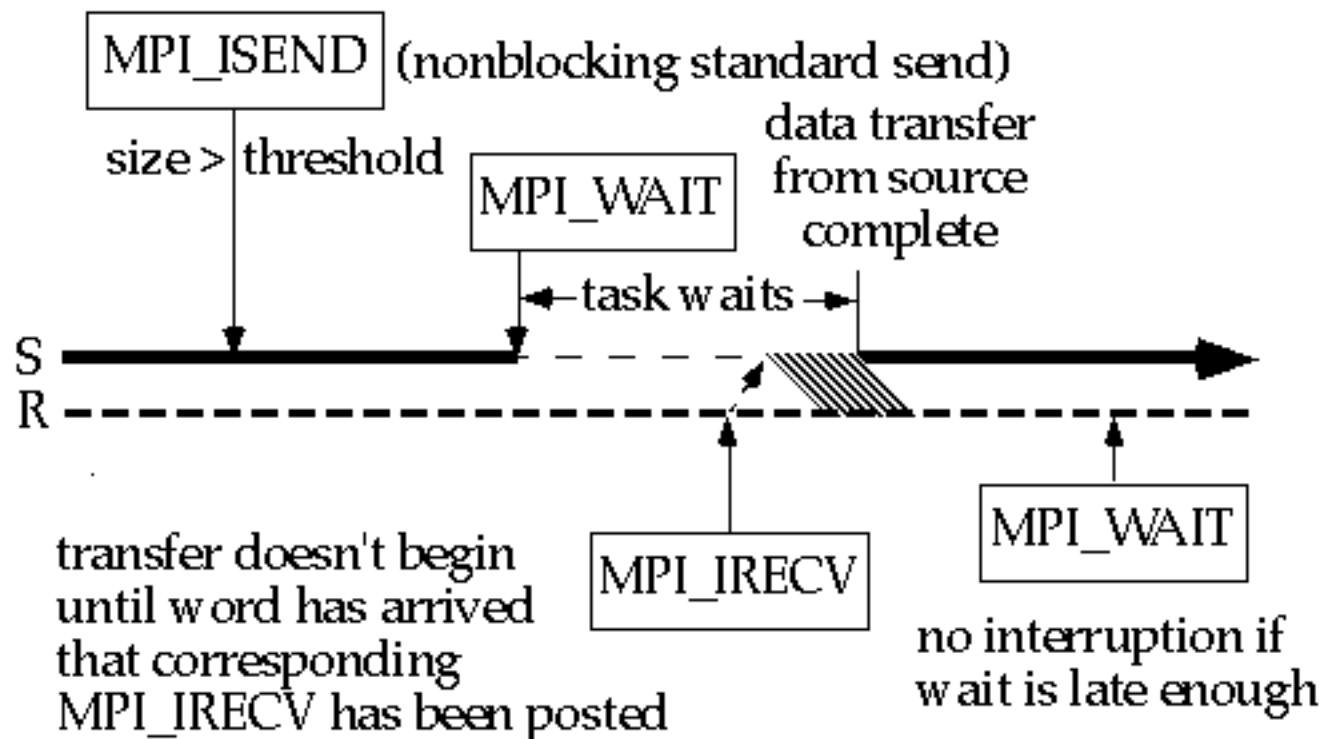
## Non-Blocking Varieties of MPI\_Send...

- **Do not access send buffer until send is complete!**
- **To check send status, call MPI\_Wait or similar checking function**
  - Every nonblocking send *must* be paired with a checking call
  - Returned “request handle” gets passed to the checking function
  - Request handle does not clear until a check succeeds
- **MPI\_Isend( buf, count, datatype, dest, tag, comm, request )**
  - Immediate non-blocking send, message goes into pending state
- **MPI\_Issend( buf, count, datatype, dest, tag, comm, request )**
  - Synchronous mode non-blocking send
  - Control returns when matching receive has begun
- **MPI\_Ibsend( buf, count, datatype, dest, tag, comm, request )**
  - Non-blocking buffered send
- **MPI\_Irsend ( buf, count, datatype, dest, tag, comm, request )**
  - Non-blocking ready send



## MPI\_Isend for Size > Threshold: Rendezvous Protocol

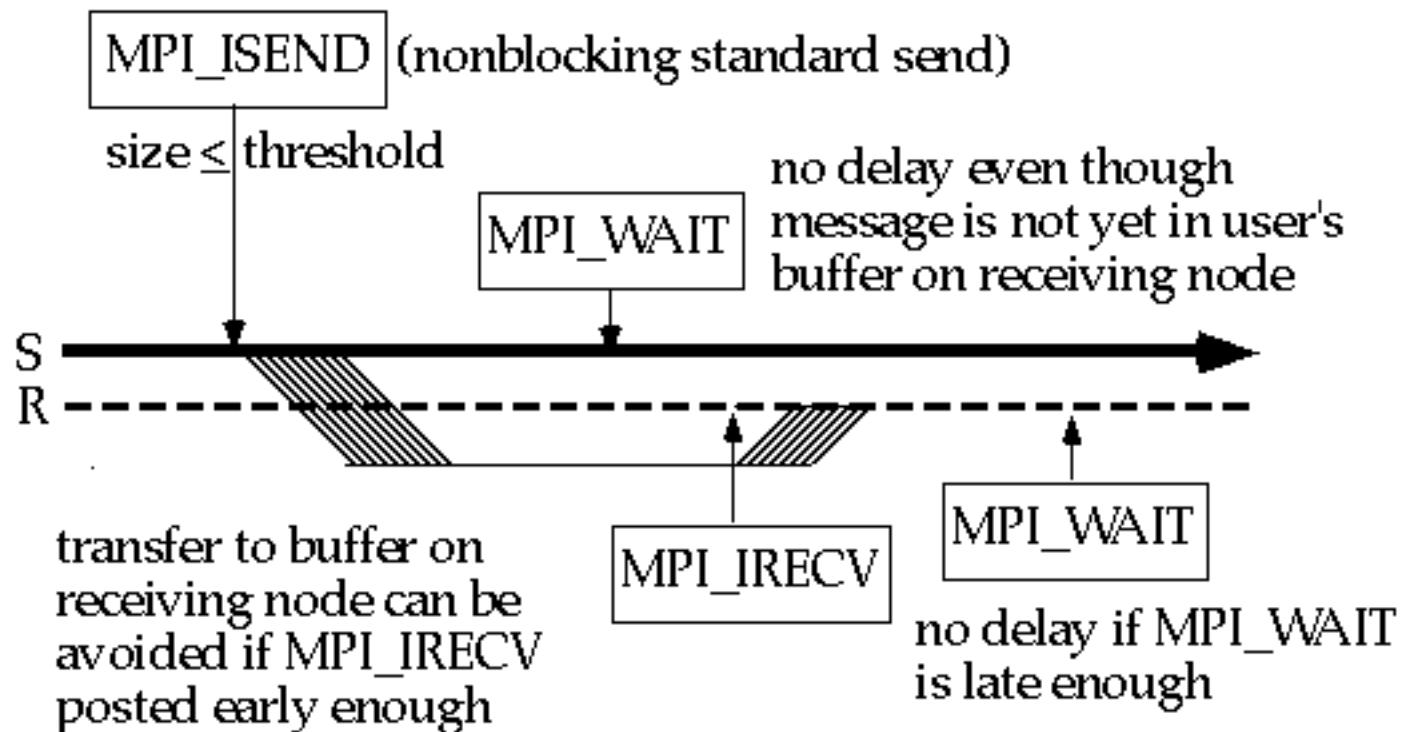
- MPI\_Wait blocks until receive has been posted
- For Intel MPI,  $\text{I\_MPI\_EAGER\_THRESHOLD}=262144$  (256K by default )





## MPI\_Isend for Size <= Threshold: Eager Protocol

- No waiting on either side if MPI\_Irecv is posted after the send...
- What if MPI\_Irecv or its MPI\_Wait is posted before the send?





## **MPI\_Recv and MPI\_Irecv**

- **`MPI_Recv( buf, count, datatype, source, tag, comm, status )`**
  - Blocking receive
- **`MPI_Irecv( buf, count, datatype, source, tag, comm, request )`**
  - Non-blocking receive
  - Make sure receive is complete before accessing buffer
- **Nonblocking call must always be paired with a checking function**
  - Returned “request handle” gets passed to the checking function
  - Request handle does not clear until a check succeeds
- **Again, use `MPI_Wait` or similar call to ensure message receipt**
  - `MPI_Wait( MPI_Request request, MPI_Status status)`



## MPI\_Irecv Example

### Task Parallelism fragment (tp1.c)

```
while(complete < iter)
{
    for (w=1; w<numprocs; w++)
    {
        if ((worker[w] == idle) && (complete < iter))
        {
            printf ("Master sending uow[%d] to worker %d\n",complete,w);
            Unit_of_Work[0] = a[complete];
            Unit_of_Work[1] = b[complete];
            // Send the Unit of Work
            MPI_Send(Unit_of_Work,2,MPI_INT,w,0,MPI_COMM_WORLD);
            // Post a non-blocking Recv for that Unit of Work
            MPI_Irecv(&result[w],1,MPI_INT,w,0,MPI_COMM_WORLD,&recv_req[w]);
            worker[w] = complete;
            dispatched++;
            complete++; // next unit of work to send out
        }
    } // foreach idle worker
    // Collect returned results
    returned = 0;
    for(w=1; w<=dispatched; w++)
    {
        MPI_Waitany(dispatched, &recv_req[1], &index, &status);
        printf("Master receiving a result back from worker %d c[%d]=%d
\ n",status.MPI_SOURCE,worker[status.MPI_SOURCE],result[status.MPI_SOURCE]);
        c[worker[status.MPI_SOURCE]] = result[status.MPI_SOURCE];
        worker[status.MPI_SOURCE] = idle;
        returned++;
    }
}
```



## **MPI\_Probe and MPI\_Iprobe**

- **MPI\_Probe**
  - `MPI_Probe( source, tag, comm, status )`
  - Blocking test for a message
- **MPI\_Iprobe**
  - `int MPI_Iprobe( source, tag, comm, flag, status )`
  - Non-blocking test for a message
- **Source can be specified or MPI\_ANY\_SOURCE**
- **Tag can be specified or MPI\_ANY\_TAG**



## **MPI\_Get\_count**

**MPI\_Get\_count(MPI\_Status \*status, MPI\_Datatype datatype, int \*count)**

- **The status variable returned by MPI\_Recv also returns information on the length of the message received**
  - This information is not directly available as a field of the MPI\_Status struct
  - A call to MPI\_Get\_count is required to “decode” this information
- **MPI\_Get\_count takes as input the status set by MPI\_Recv and computes the number of entries received**
  - The number of entries is returned in count
  - The datatype argument should match the argument provided to the receive call that set status
  - Note: in Fortran, status is simply an array of INTEGERs of length MPI\_STATUS\_SIZE



## **MPI\_Sendrecv**

- **Combines a blocking send and a blocking receive in one call**
- **Guards against deadlock**
- **MPI\_Sendrecv**
  - Requires two buffers, one for send, one for receive
- **MPI\_Sendrecv\_replace**
  - Requires one buffer, received message overwrites the sent one
- **For these combined calls:**
  - Destination (for send) and source (of receive) can be the same process
  - Destination and source can be different processes
  - MPI\_Sendrecv can send to a regular receive
  - MPI\_Sendrecv can receive from a regular send
  - MPI\_Sendrecv can be probed by a probe operation



## BagBoy Example

### 1 of 3

```
#include <stdio.h>
#include <mpi.h>
#include <stdlib.h>
#include <time.h>
#include <malloc.h>
#define Products 10

int main(int argc, char **argv )
{
    int myid,numprocs;
    int true = 1;
    int false = 0;
    int messages = true;
    int i,g,items,flag;
    int *customer_items;
    int checked_out = 0;
    /* Note, Products below are defined in order of increasing weight */
    char Groceries[Products][20] = {"Chips","Lettuce","Bread","Eggs","Pork
        Chops","Carrots","Rice","Canned Beans","Spaghetti Sauce","Potatoes"};
    MPI_Status status;

    MPI_Init(&argc, &argv);
    MPI_Comm_size(MPI_COMM_WORLD,&numprocs);
    MPI_Comm_rank(MPI_COMM_WORLD,&myid);
```



## BagBoy Example

### 2 of 3

```
if (numprocs >= 2)
{
    if (myid == 0) // Master
    {
        customer_items = (int *) malloc(numprocs * sizeof(int));
        /* initialize customer items to zero - no items received yet */
        for (i=1;i<numprocs;i++) customer_items[i]=0;
        while (messages)
        {
            MPI_Iprobe(MPI_ANY_SOURCE,MPI_ANY_TAG,MPI_COMM_WORLD,&flag,&status);
            if (flag)
            {
                MPI_Recv(&items,
1,MPI_INT,status.MPI_SOURCE,status.MPI_TAG,MPI_COMM_WORLD,&status);
                /* increment the count of customer items from this source */
                customer_items[status.MPI_SOURCE]++;
                if (customer_items[status.MPI_SOURCE] == items) checked_out++;
                printf("%d: Received %20s from %d, item %d of %d
\n",myid,Groceries[status.MPI_TAG],status.MPI_SOURCE,customer_items[status.MP
I_SOURCE],items);
            }
            if (checked_out == (numprocs-1)) messages = false;
        }
    } // Master
```



## BagBoy Example

### 3 of 3

```
else // workers
{
    srand((unsigned)time(NULL)+myid);
    items = (rand() % 5) + 1;
    for(i=1;i<=items;i++)
    {
        g = rand() % 10;
        printf("%d: Sending %s, item %d of %d\n",myid,Groceries[g],i,items);
        MPI_Send(&items,1,MPI_INT,0,g,MPI_COMM_WORLD);
    }
} // workers
}
else
printf("ERROR: Must have at least 2 processes to run\n");

MPI_Finalize();
return 0;
}
```



## Using Message Passing Interface, MPI Bubble Sort

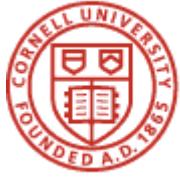


## Bubble Sort

```
#include <stdio.h>
#define N 10

int main (int argc, char *argv[])
{
    int a[N];
    int i,j,tmp;

    printf("Unsorted\n");
    for (i=0; i<N; i++) { a[i] = rand(); printf("%d\n",a[i]); }
    for (i=0; i<(N-1); i++)
        for(j=(N-1); j>i; j--)
            if (a[j-1] > a[j])
            {
                tmp = a[j];
                a[j] = a[j-1];
                a[j-1] = tmp;
            }
    printf("\nSorted\n");
    for (i=0; i<N; i++) printf("%d\n",a[i]);
}
```



## Serial Bubble Sort in Action

$N = 5$

3 8 4 5 2

i=0, j=4

3 8 4 2 5

i=0, j=3

3 8 2 4 5

i=0, j=2

3 2 8 4 5

i=0, j=1

2 3 8 4 5

i=1, j=4

2 3 8 4 5

i=1, j=3

2 3 4 8 5

i=1, j=2

2 3 4 8 5

i=2, j=4

2 3 4 5 8

i=2, j=3

2 3 4 5 8



## Step 1: Partitioning

### Divide Computation & Data into Pieces

- The primitive task would be each element of the unsorted array

#### Goals:

- ✓ Order of magnitude more primitive tasks than processors
- ✓ Minimization of redundant computations and data
- ✓ Primitive tasks are approximately the same size
- ✓ Number of primitive tasks increases as problem size increases



## Step 2: Communication

### Determine Communication Patterns between Primitive Tasks

- **Each task communicates with its neighbor on each side**

#### Goals:

- ✓ **Communication is balanced among all tasks**
- ✓ **Each task communicates with a minimal number of neighbors**
- ✓ **\*Tasks can perform communications concurrently**
- ✓ **\*Tasks can perform computations concurrently**

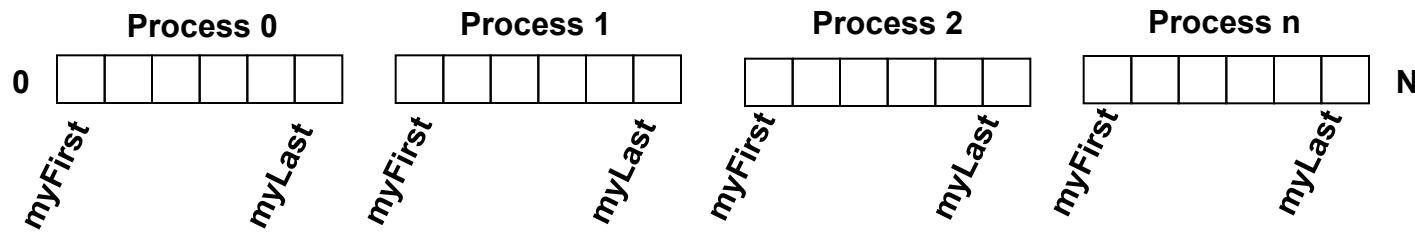
\*Note: there are some exceptions in the actual implementation



## Step 3: Agglomeration

### Group Tasks to Improve Efficiency or Simplify Programming

- Divide unsorted array evenly amongst processes
- Perform sort steps in parallel
- Exchange elements with other processes when necessary

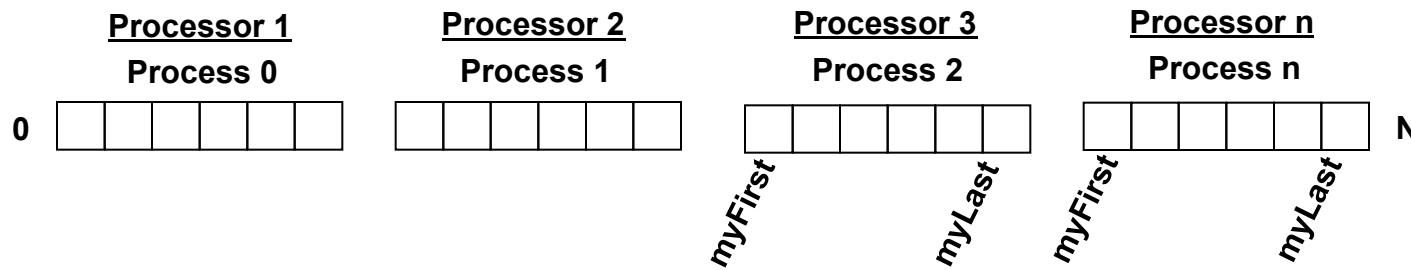


- ✓ Increases the locality of the parallel algorithm
- ✓ Replicated computations take less time than the communications they replace
- ✓ Replicated data is small enough to allow the algorithm to scale
- ✓ Agglomerated tasks have similar computational and communications costs
- ✓ Number of tasks can increase as the problem size does
- ✓ Number of tasks as small as possible but at least as large as the number of available processors
- ✓ Trade-off between agglomeration and cost of modifications to sequential codes is reasonable



## Step 4: Mapping Assigning Tasks to Processors

- Map each process to a processor
- This is not a CPU intensive operation so using multiple tasks per processor should be considered
- If the array to be sorted is very large, memory limitations may compel the use of more machines

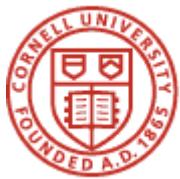


- ✓ Mapping based on one task per processor and multiple tasks per processor have been considered
  - ✓ Both static and dynamic allocation of tasks to processors have been evaluated
- (NA) If a dynamic allocation of tasks to processors is chosen, the task allocator (master) is not a bottleneck
- ✓ If static allocation of tasks to processors is chosen, the ratio of tasks to processors is at least 10 to 1



## Hint – Sketch out Algorithm Behavior *BEFORE* Implementing 1 of 2

7	6	5	4		3	2	1	0
j=3					j=7			
7	6	4	5		3	2	0	1
j=2					j=6			
7	4	6	5		3	0	2	1
j=1					j=5			
4	7	6	5		0	3	2	1
j=0					j=4			
				<->				
4	7	6	0		5	3	2	1
j=3					j=7			
4	7	0	6		5	3	1	2
j=2					j=6			
4	0	7	6		5	1	3	2
j=1					j=5			
0	4	7	6		1	5	3	2
j=0					j=4			
				<->				
0	4	7	1		6	5	3	2
j=3					j=7			
0	4	1	7		6	5	2	3
j=2					j=6			
0	1	4	7		6	2	5	3
j=1					j=5			
0	1	4	7		2	6	5	3
j=0					j=4			
				<->				



## Hint 2 of 2

0	1	4	2		7	6	5	3
j=3					j=7			
0	1	2	4		7	6	3	5
j=2					j=6			
0	1	2	4		7	3	6	5
j=1					j=5			
0	1	2	4		3	7	6	5
j=0					j=4			
				<->				
0	1	2	3		4	7	6	5
j=3					j=7			
0	1	2	3		4	7	5	6
j=2					j=6			
0	1	2	3		4	5	7	6
j=1					j=5			
0	1	2	3		4	5	7	6
j=0					j=4			
				<->				
0	1	2	3		4	5	7	6
j=3					j=7			
0	1	2	3		4	5	6	7
j=2					j=6			
0	1	2	3		4	5	6	7
j=1					j=5			
0	1	2	3		4	5	6	7
j=0					j=4			

...?... <-> how many times?...